









 <h1 data-bbox="491 526 782 593">AGORA</h1> <p data-bbox="491 600 1053 672">Intermodal Terminals Marco Polo Common Learning Project</p>	
<p data-bbox="341 723 865 757">Positioning of Mobile Cranes in Terminals</p> <p data-bbox="341 763 742 797">Ulrich Altmann, Neuss Trimodal</p> <p data-bbox="341 804 778 840">Erich Possegger, Rail Cargo Austria</p>	
<p data-bbox="341 884 518 918">Final Seminar</p> <p data-bbox="341 925 849 958">Frankfurt am Main - November 9, 2010</p>	
 <p data-bbox="1145 853 1246 873">Neuss Trimodal</p>  <p data-bbox="1123 936 1268 963">2010-11-09 Chart 1</p>	


	
<h2 data-bbox="331 1350 582 1395">Terminal Neuss</h2>	
<p data-bbox="386 1429 630 1462">Inland trimodal terminal</p> <p data-bbox="386 1469 550 1503">Area 133 000 m².</p> <p data-bbox="386 1509 646 1543">2 cranes, 8 reach stackers</p> <p data-bbox="386 1550 742 1608">Empty container are stacked up to 5 high.</p>	 
<p data-bbox="694 1921 901 1944">Symeo - Absolute Positioning</p>	
 <p data-bbox="1145 1785 1246 1805">Neuss Trimodal</p>  <p data-bbox="1123 1868 1268 1895">2010-10-22 Chart 2</p>	







Terminal Wels

Inland gateway-terminal
 Area 110 000 m²
 6 Tracks a' 580m
 2 cranes, 5 reach stackers
 High percentage rail/rail handling






Neuss Trimodal




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2010-10-22
Chart 3

Symeo - Absolute Positioning

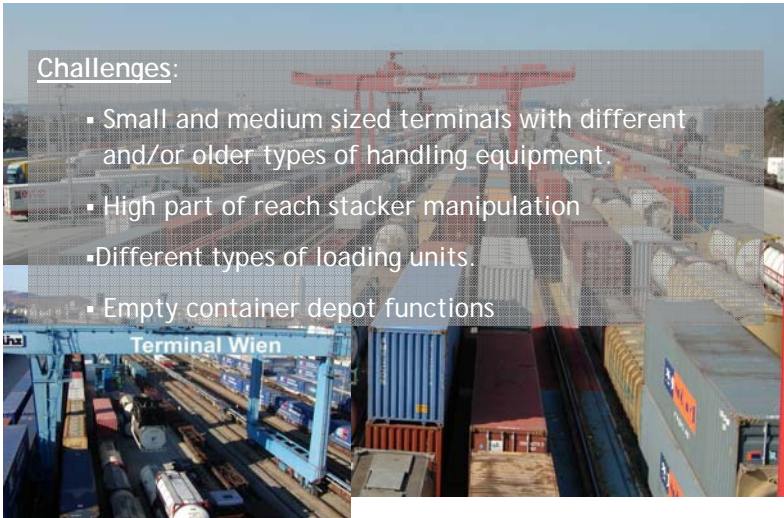





Terminal Wels and RCA Terminals


Challenges:

- Small and medium sized terminals with different and/or older types of handling equipment.
- High part of reach stacker manipulation
- Different types of loading units.
- Empty container depot functions







Neuss Trimodal

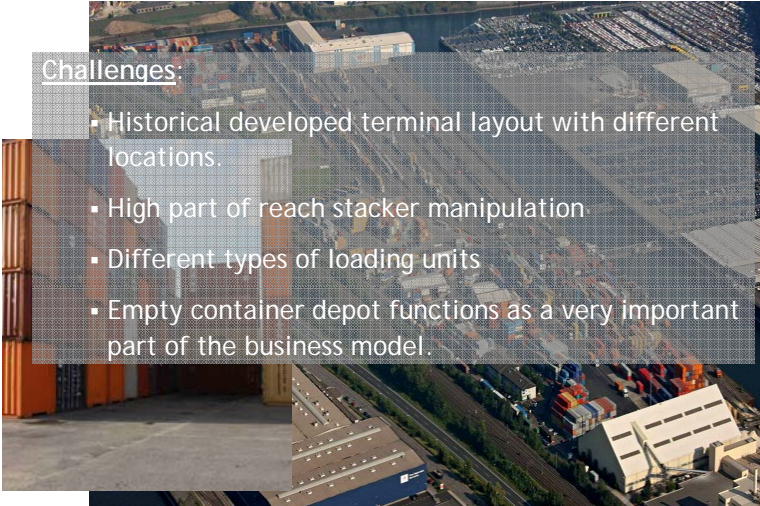


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Chart 4





Terminal Neuss




Challenges:



- Historical developed terminal layout with different locations.
- High part of reach stacker manipulation.
- Different types of loading units
- Empty container depot functions as a very important part of the business model.



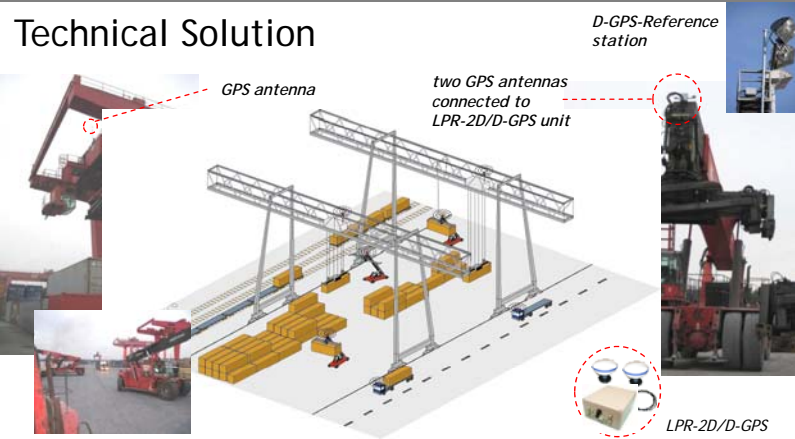
Neuss Trimodal




2010-10-22
Chart 5


Technical Solution



- Tracking all container movements and positions by continuous position measurement of all cranes and reach stackers on the yard.
- D-GPS is applied as positioning accuracy is sufficient and satellite signal is uncompromised.
- The LPR-2D option with local transponders enables tracking in shielded and indoor areas to provide seamless position information



Neuss Trimodal



2010-10-22
Chart 6

MARCO POLO AGORA GROUP FOR A GREENER FUTURE

AGORA

Positioning Equipment Reach Stacker

SYMEO ABSOLUTE POSITIONING

LPR-I/O Module

D-GPS system with ZigBee Interface

ZigBee Receiver (connected to TOS-terminal)

Load sensor (inductive and ultrasonic)

— wire connection
- - - Wireless (ZigBee)

Neuss Trimodal

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Chart 7

MARCO POLO AGORA GROUP FOR A GREENER FUTURE


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GPS Antenna - Location

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Chart 8





Positioning Equipment Cranes

- Position of crane via D-GPS
- Trolley-position via LPR
- Wireless comm. Between components



D-GPS +1 Antenne




LPR +1 Antenne

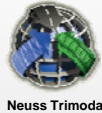


LPR +1 Antenne



I/O SPS







Neuss Trimodal



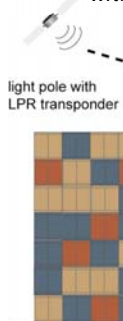
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2010-10-22
Chart 9

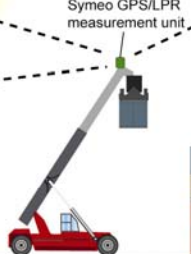



Solution for underdetermined GPS Positions


Problem: Not enough (<4) satellites or LPR transponders (<3) for each system within range.




light pole with LPR transponder



Symeo GPS/LPR measurement unit

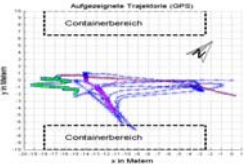


GPS satellite

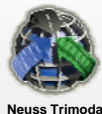


Solution:


- Symeo Sensor-Fusion combines existing satellite and transponder signals to determine the dynamic position



Aufgezeichnete Trajektorie (GPS)
Containerbereich













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2010-10-22
Chart 10

	
<h2>Status of the projects</h2>	
<ul style="list-style-type: none"> ■ Neuss Trimodal: <ul style="list-style-type: none"> ▪ Test trails with additional sensors for poor satellite visibility 2010. ▪ Implementation of the system including existing portal crane together with new Terminal Management System beginning with 2011. ■ RCA Wels / RCA Terminals: <ul style="list-style-type: none"> ▪ Positioning system incl. extended Terminal Management System in operation since 11/2009. ▪ Roll out to all other terminals of RCA-Group (incl. Budapest) planned up to 09/2011. ▪ Pilot installation of Empty Container handling equipment during system implementation in Wolfurt 02/2011. 	
 <p>Neuss Trimodal</p>  <p>2010-10-22 Chart 11</p>	

	
	<p>Thank You for your attention ...</p>
	
 <p>Neuss Trimodal</p>  <p>2010-10-22 Chart 12</p>	